This is the Revision A version of the ShaftSense2 RoboBrick. The status of this project is work in progress.

ShaftSense2 Robobrick (Revision A)

Table of Contents

This document is also available in <u>PDF</u> format.

- 1. Introduction
- 2. Programming
- 3. Hardware
 - ♦ 3.1 Circuit Schematic
 - ♦ 3.2 Printed Circuit Board
- 4. Software
- <u>5. Issues</u>

1. Introduction

The ShaftSense2 board is designed to pick up a quadrature signal from a shaft using two Hamamatsu P5507 chips.

2. Programming

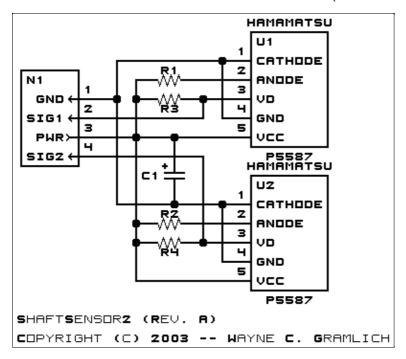
There is no programming specification yet.

3. Hardware

The hardware consists of a circuit schematic and a printed circuit board.

3.1 Circuit Schematic

The schematic for the ShaftSense2 RoboBrick is shown below:



The parts list kept in a separate file — shaftsense2.ptl.

3.2 Printed Circuit Board

The printed circuit board files are listed below:

shaftsense2 back.png

The solder side layer.

shaftsense2 front.png

The component side layer.

shaftsense2 artwork.png

The artwork layer.

shaftsense2.gbl

The RS-272X "Gerber" back (solder side) layer.

shaftsense2.gtl

The RS-272X "Gerber" top (component side) layer.

shaftsense2.gal

The RS-272X "Gerber" artwork layer.

shaftsense2.drl

The "Excellon" NC drill file.

shaftsense2.tol

The "Excellon" tool rack file.

4. Software

There is no software yet.

5. Issues

Any fabrication issues that come up are listed here.

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5. Issues 3

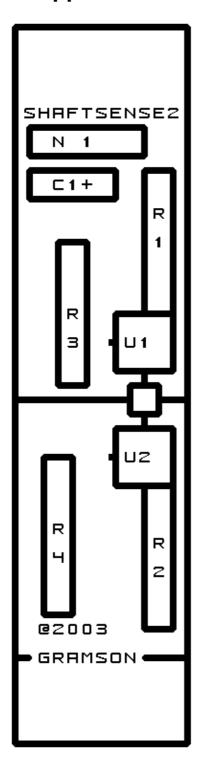
ShaftSense2 RoboBrick (Revision A)

5. Issues 4

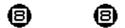
A. Appendix A: Parts List

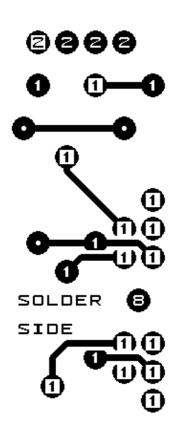
```
# Parts list for ShaftSense2 (Rev. A)
#
C1: Capacitor100nF - .1 uF Capacitor [Jameco: 25524]
N1: Header1x4.ShaftSense2 [4/40 Jameco: 160881]
R1-2: Resistor10K - 10K KOhm 1/4 Watt Resistor [Jameco: 29911]
R3-4: Resistor470 - 470 Ohm 1/4 Watt Resistor [Jameco: 31165]
U1-2: P5587 - Hamamatsu Photoreflector [Acroname: R65-P5587]
```

B. Appendix B: Artwork Layer



C. Appendix C: Back (Solder Side) Layer







8 8

D. Appendix D: Front (Component Side) Layer



