This is the Revision A version of the <u>Out10 RoboBrick</u>. The status of this project is that it has been <u>replaced</u> by the <u>InOut10 RoboBrick</u>.

Out10 Robobrick (Revision A)

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1. Introduction

The Out10 RoboBrick provides the ability to output 10 bits of data.

A picture of an Out10–A RoboBrick is shown below:



2. Programming

The Out10 RoboBrick supports the standard shared commands in addition to the following commands:

Command	Send/Receive			By	vte '	Val	ue			Discussion
		7	6	5	4	3	2	1	0	

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								-		
Write Lower	Send	0	0	0	f	g	h	i	j	Write <i>fghij</i> out to the lower 5 bits.
Write Upper	Send	0	0	1	а	b	с	d	е	Write <i>abcde</i> out to the upper 5 bits.
Bit Clear	Send	0	1	0	0	b	b	b	b	Turn bit <i>bbbb</i> off. MSB (<i>bbbb</i> =1010) LSB (<i>bbbb</i> =0000)
Bit Set	Send	0	1	0	1	b	b	b	b	Turn bit <i>bbbb</i> on.
Bit Toggle	Send	0	1	1	0	b	b	b	b	Toggle bit <i>bbbb</i> .
Bit Read	Send	0	1	1	1	b	b	b	b	Read status of bit bbbb.
	Receive	0	0	0	0	0	0	0	b	Bit state is <i>b</i> .
Read All	Send	1	0	0	0	0	0	0	0	Read all ten bits.
	Receive	0	0	0	а	b	с	d	е	Upper five bits abcde
	Receive	0	0	0	f	g	h	i	j	Lower five bits <i>fghij</i>
Read Lower	Send	1	0	0	0	0	0	0	1	Read lower five bits.
	Receive	0	0	0	f	g	h	i	j	Lower five bits are fghij
Read Upper	Send	1	0	0	0	0	0	1	0	Read upper five bits.
	Receive	0	0	0	а	b	с	d	е	Upper five bits are <i>abcde</i>
Increment Bits	Send	1	0	0	1	b	b	b	b	Increment bits starting at bit <i>bbbb</i>
Decrement Bits	Send	1	0	1	0	b	b	b	b	Decrement bits starting at bit bbbb
Shared Commands	Send	1	1	1	1	1	а	b	с	Send shared command <i>abc</i> to RoboBrick.

3. Hardware

The hardware consists of a circuit schematic and a printed circuit board.

3.1 Circuit Schematic

The schematic for the Out10 RoboBrick is shown below:



The parts list kept in a separate file --<u>out10.ptl</u>.

3.2 Printed Circuit Board

The printed circuit files are listed below:

```
out10 back.png
       The solder side layer.
out10 front.png
       The component side layer.
out10 artwork.png
       The artwork layer.
out10.gbl
       The RS-274X "Gerber" back (solder side) layer.
out10.gtl
       The RS-274X "Gerber" top (component side) layer.
out10.gal
       The RS-274X "Gerber" artwork layer.
out10.drl
       The "Excellon" NC drill file.
out10.tol
       The "Excellon" tool rack file.
```

4. Software

The Out10 software is available as one of:

out10.ucl

3.2 Printed Circuit Board

The µCL source file.

out10.asm

The resulting human readable PIC assembly file.

<u>out10.lst</u>

The resulting human readable PIC listing file.

out10.hex

The resulting Intel[®] Hex file that can be fed into a PIC12C5xx programmer.

The Out10 test suite is available as one of:

out10 test.ucl

The µCL source file.

<u>out10 test.asm</u>

The resulting human readable PIC assembly file.

out10 test.lst

The resulting human readable PIC listing file.

out10 test.hex

The resulting Intel[®] Hex file that can be fed into a PIC16F84 programmer.

5. Issues

The following issues came up:

- Add labels to output pins in copper.
- Remove RJ11 connector.
- Remove capacitor.

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Out10 RoboBrick (Revision A)

A. Appendix A: Parts List

Parts list for Out10 RoboBrick (Rev. A)
#
C1: Capacitor10pF - 10 pF Ceramic Capacitor [Jameco: 15333]
C2: Capacitor2200uF - 2200 uF 6.3V Electrolytic Capacitor [Jameco: 133145]
N1: RJ11Female4_4.RBSlave - Female RJ11 (4-4) Phone Jack [Digikey: A9071-ND]
N2: TerminalStrip8.Out10 - 8 Junction Terminal Strip [4 Jameco: 189675]
N3: TerminalStrip4.Out10 - 4 Junction Terminal Strip [2 Jameco: 189675]
U1: PIC16C505.Out10 - Microchip PIC16C505 [Digikey: PIC16C505-04/P-ND]

B. Appendix B: Artwork Layer







D. Appendix D: Front (Component Side) Layer

