This is the Revision A version of the InOut10 RoboBrick. The status of this project is that it has been replaceed by the revision C version.

InOut10 Robobrick (Revision B)

Table of Contents

This document is also available in PDF format.

1. Introduction

The InOut10 RoboBrick provides the ability to input and output 10 bits of data. The direction of each bit can be changed under program control.

2. Programming

The basic operation is to send a query to the In8 RoboBrick to read the 4 bits of data. The programmer can download a complement mask to cause any of the bits to be complemented prior to reading.

The In8 RoboBrick supports RoboBrick Interrupt Protocol. The interrupt pending bit is set whenever the the formula:

L&(~I) | H&I | R&(~P)&I | F&P&(~I)]

is non−zero, where:

- I is the current input bits XOR'ed with the complement mask (C)
- P is the previous value of I
- L is the low mask
- H is the high mask
- R is the raising mask
- F is the falling mask

and

- ~ is bit−wise complement
- | is bit−wise OR
- & is bit−wise AND

Once the interrupt pending bit is set, it must be explicitly cleared by the user.

The In8 RoboBrick supports both the standard shared commands and the shared interrupt commands in addition to the following commands:

Command	Send/ Receive	7	6	5	4	3	2	1	0	Discussion
Read Inputs Low	Send	0	0	0	0	0	0	0	0	Return low order 5−bits of input *iiiii* (after XOR'ing with complement mask)
	Receive	0	0	0	*i*	*i*	*i*	*i*	*i*	
Read Inputs High	Send	0	0	0	0	0	0	0	1	Return high order 5−bits of input *IIIII* (after XOR'ing with complement mask)
	Receive	0	0	0	*I*	*I*	*I*	*I*	*I*	
Read Complement Mask Low	Send	0	0	0	0	0	0	1	0	Return low order 5−bits of complement mask *ccccc*
	Receive	0	0	0	*c*	*c*	*c*	*c*	*c*	
Read Complement Mask High	Send	0	0	0	0	0	0	1	1	Return high order 5 bits of complement mask *CCCCC*
	Receive	0	0	0	*C*	*C*	*C*	*C*	*C*	
Read Direction Mask Low	Send	0	0	0	0	0	1	0	0	Return low order 5−bits of direction mask *ddddd*
	Receive	0	0	0	*d*	*d*	*d*	*d*	*d*	
Read Direction Mask High	Send	0	0	0	0	0	1	0	1	Return high order 5 bits of direction mask *DDDDD*
	Receive	0	0	0	*D*	*D*	*D*	*D*	*D*	
Read Raw Low	Send	0	0	0	0	0	1	1	0	Return low order 5−bits of raw input data *rrrrr* (without XOR'ing with complement mask)
	Receive	0	0	0	*r*	*r*	*r*	*r*	*r*	
Read Raw High	Send	0	0	0	0	0	1	1	1	Return high order 5−bits of raw input data *RRRRR* (without XOR'ing with complement mask)
	Receive	0	0	0	*R*	*R*	*R*	*R*	*R*	
Read Low Mask Low	Send	0	0	0	0	1	0	0	0	Return low order 5−bits of low mask *lllll*
	Receive	0	0	0	*l*	*l*	*l*	*l*	*l*	
Read Low Mask High	Send	0	0	0	0	1	0	0	1	Return high order 5−bits of low mask *LLLLL*
	Receive	0	0	0	*L*	*L*	*L*	*L*	*L*	
Read High Mask Low	Send	0	0	0	0	1	0	1	0	Return low order 5−bits of the high mask *hhhhh*
	Receive	0	0	0	*h*	*h*	*h*	*h*	*h*	
Read High Mask High	Send	0	0	0	0	1	0	1	1	Return high order 5 bits of the high mask *HHHHH*
	Receive	0	0	0	*H*	*H*	*H*	*H*	*H*	
Read Raising Mask Low	Send	0	0	0	0	1	1	0	0	Return low order 5−bits of the raising mask *rrrrr*
	Receive	0	0	0	*r*	*r*	*r*	*r*	*r*	
Read Raising Mask High	Send	0	0	0	0	1	1	0	1	Return high order 5 bits of the raising mask *RRRRR*
	Receive	0	0	0	*R*	*R*	*R*	*R*	*R*	
Read Falling Mask Low	Send	0	0	0	0	1	1	1	0	Return low order 5−bits of the falling mask *fffff*
	Receive	0	0	0	*f*	*f*	*f*	*f*	*f*	
Read Falling Mask High	Send	0	0	0	0	1	1	1	1	Return high order 5−bits of the falling mask *FFFFF*
	Receive	0	0	0	*F*	*F*	*F*	*F*	*F*	
Read Outputs Low	Send	0	0	0	1	0	0	0	0	

Command	Dir	b7	b6	b5	b4	b3	b2	b1	b0	Description
	Receive	0	0	0	o	o	o	o	o	Return low order 5–bits of the outputs ooooo
Read Outputs High	Send	0	0	0	1	0	0	0	1	Return high order 5–bits of the outputs OOOOO
	Receive	0	0	0	O	O	O	O	O	
Set Complement Mask Low	Send	0	0	0	1	0	0	1	0	Set low order 5–bits of complement mask to ccccc
	Send	0	0	0	c	c	c	c	c	
Set Complement Mask High	Send	0	0	0	1	0	0	1	1	Set high order 5 bits of complement mask to CCCCC
	Send	0	0	0	C	C	C	C	C	
Set Direction Mask Low	Send	0	0	0	1	0	1	0	0	Set low order 5–bits of direction mask to ddddd
	Send	0	0	0	d	d	d	d	d	
Set Direction Mask High	Send	0	0	0	1	0	1	0	1	Set high order 5 bits of direction mask of DDDDD
	Send	0	0	0	D	D	D	D	D	
Reset Outputs	Send	0	0	0	1	0	1	1	0	Set all 10 bits of outputs to 0
Reset Everything	Send	0	0	0	1	0	1	1	1	Reset all registers to 0 and set direction bits to 1 (input)
Set Low Mask Low	Send	0	0	0	1	1	0	0	0	Set low order 5–bits of low mask to lllll
	Send	0	0	0	l	l	l	l	l	
Set Low Mask High	Send	0	0	0	1	1	0	0	1	Set high order 5–bits of low mask to LLLLL
	Send	0	0	0	L	L	L	L	L	
Set High Mask Low	Send	0	0	0	1	1	0	1	0	Set low order 5–bits of the high mask to hhhhh
	Send	0	0	0	h	h	h	h	h	
Set High Mask High	Send	0	0	0	1	1	0	1	1	Set high order 5 bits of the high mask to HHHHH
	Send	0	0	0	H	H	H	H	H	
Set Raising Mask Low	Send	0	0	0	1	1	1	0	0	Set low order 5–bits of the raising mask to rrrrr
	Send	0	0	0	r	r	r	r	r	
Set Raising Mask High	Send	0	0	0	1	1	1	0	1	Set high order 5 bits of the raising mask to RRRRR
	Send	0	0	0	R	R	R	R	R	
Set Falling Mask Low	Send	0	0	0	1	1	1	1	0	Set low order 5–bits of the falling mask to fffff
	Send	0	0	0	f	f	f	f	f	
Set Falling Mask High	Send	0	0	0	1	1	1	1	1	Set high order 5–bits of the falling mask to FFFFF
	Send	0	0	0	F	F	F	F	F	
Set Outputs Low	Send	0	0	1	o	o	o	o	o	Set low order 5–bits to ooooo
Set Outputs High	Send	0	1	0	O	O	O	O	O	Set high order 5–bits to OOOOO
Set Output Bit	Send	0	1	1	v	b	b	b	b	Set output bit bbbb to v
Read Interrupt Bits	Send	1	1	1	0	1	1	1	1	Return the interrupt pending bit p and the interrupt enable bit e.
	Receive	0	0	0	0	0	0	e	p	
[Set Interrupt Commands](#)	Send	1	1	1	1	0	c	c	c	Set Interrupt Command ccc.
[Shared Commands](#)	Send	1	1	1	1	1	c	c	c	Execute Shared Command ccc.

3. Hardware

The hardware consists of a circuit schematic and a printed circuit board.

3.1 Circuit Schematic

The schematic for the InOut10 RoboBrick is shown below:
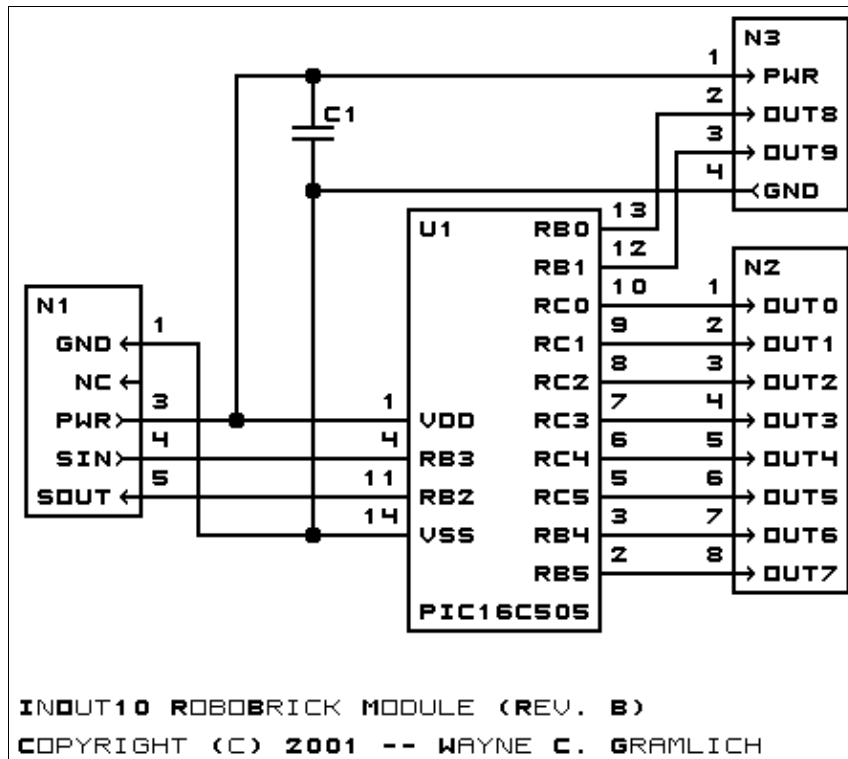
The parts list kept in a separate file –– inout10.ptl.

3.2 Printed Circuit Board

The printed circuit files are listed below:

inout10_back.png
  The solder side layer.
inout10_front.png
  The component side layer.
inout10_artwork.png
  The artwork layer.
inout10.gbl
  The RS−274X "Gerber" back (solder side) layer.
inout10.gtl
  The RS−274X "Gerber" top (component side) layer.
inout10.gal
  The RS−274X "Gerber" artwork layer.
inout10.drl

The "Excellon" NC drill file.

inout10.tol
> The "Excellon" tool rack file.

4. Software

The InOut10 software is available as one of:

inout10.ucl
> The μCL source file.

inout10.asm
> The resulting human readable PIC assembly file.

inout10.lst
> The resulting human readable PIC listing file.

inout10.hex
> The resulting Intel® Hex file that can be fed into a PIC12C5xx programmer.

The InOut10 test suite is available as one of:

inout10_test.ucl
> The μCL source file.

inout10_test.asm
> The resulting human readable PIC assembly file.

inout10_test.lst
> The resulting human readable PIC listing file.

inout10_test.hex
> The resulting Intel® Hex file that can be fed into a PIC16F84 programmer.

5. Issues

The following fabrication issues came up:

- Think about adding some in−line 220 Ohm resistors for powering LED's.
- Think about adding some 10K Ohm pull up resistors for bump sensors.

A. Appendix A: Parts List

```
# Parts list for InOut10 RoboBrick (Rev. B)
#
C1: Capacitor10pF – 10 pF Ceramic Capacitor [Jameco: 15333]
N1: Header1x5.RBSlave – 1x5 Male Header [5/40 Jameco: 160881]
N2: TerminalStrip8.InOut10 – 8 Junction Terminal Strip [4 Jameco: 189675]
N3: TerminalStrip4.InOut10 – 4 Junction Terminal Strip [2 Jameco: 189675]
U1: PIC16C505.InOut10 – Microchip PIC16C505 [Digikey: PIC16C505-04/P-ND]
```

B. Appendix B: Artwork Layer
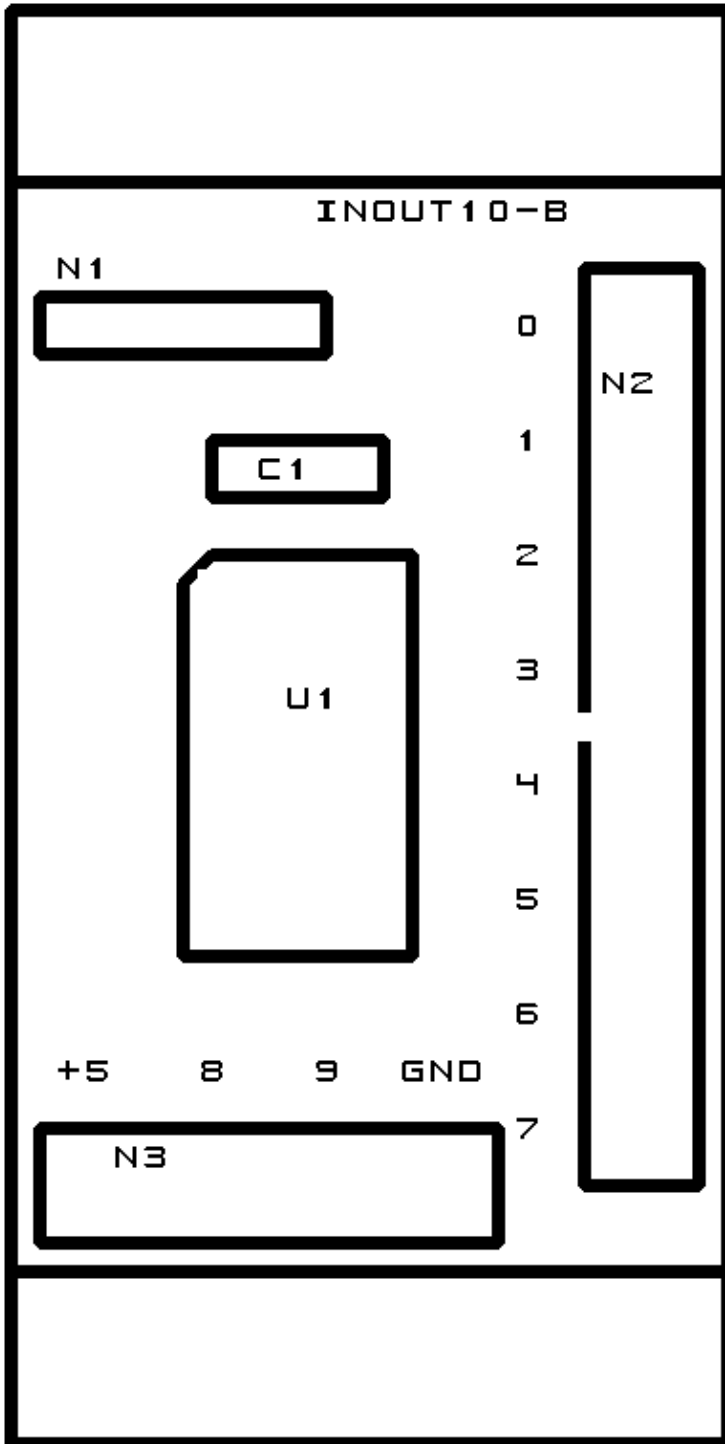
C. Appendix C: Back (Solder Side) Layer
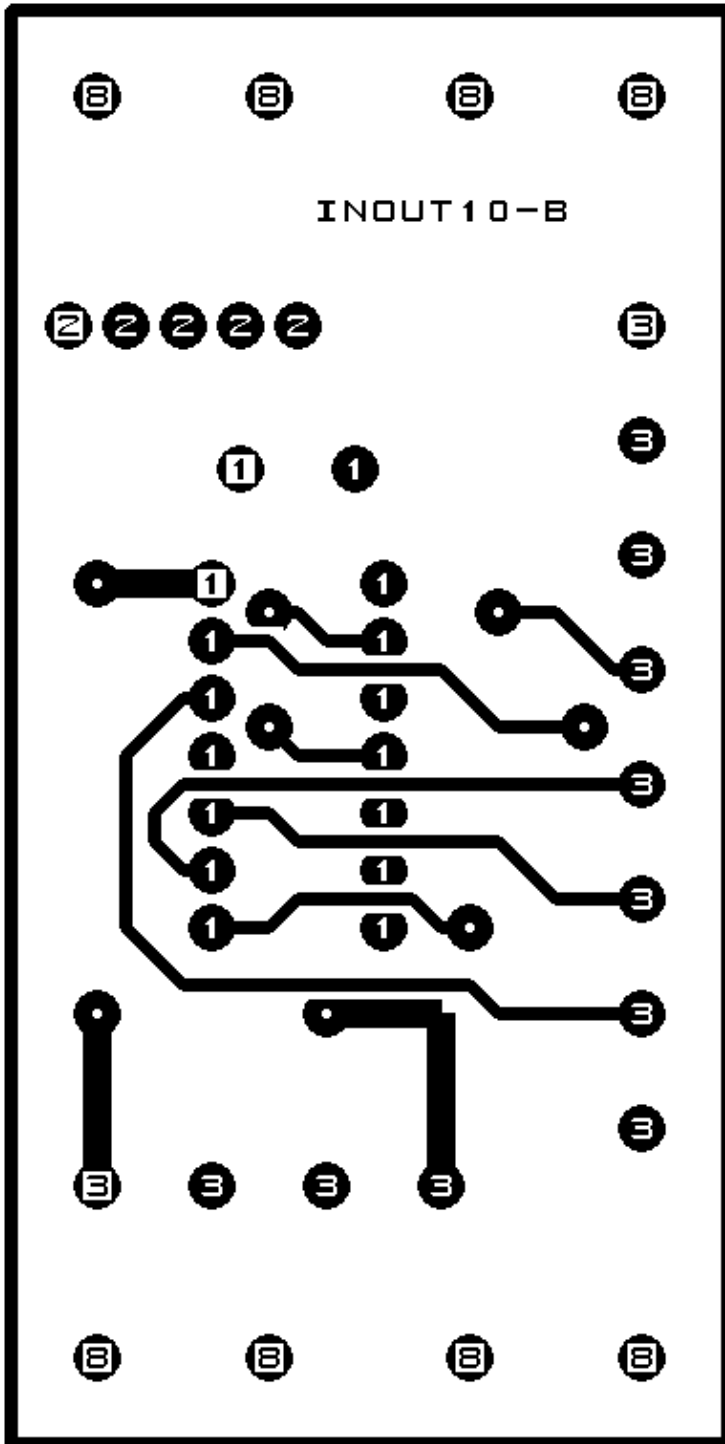
D. Appendix D: Front (Component Side) Layer